

FIG. 1A

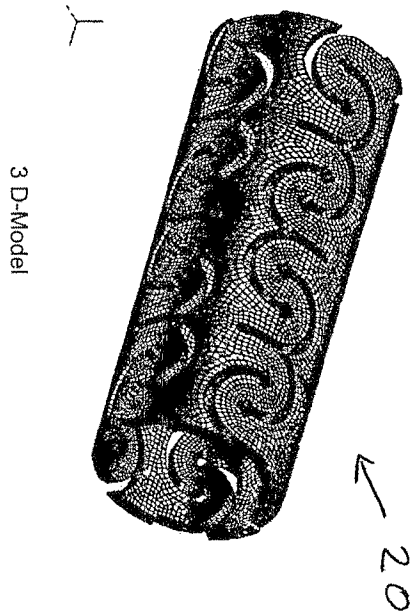
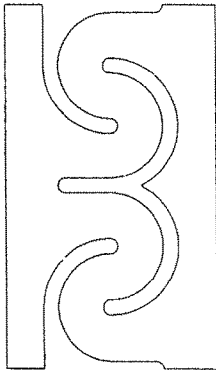


FIG. 1B

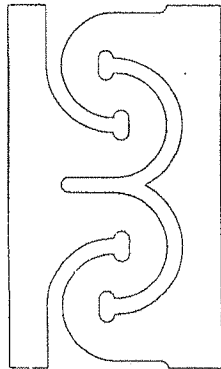
Inventor: Schlun et al.  
Application No. 10/535,081  
Replacement Drawings

Figure 1 is a schematic diagram of a multi-link mechanism. It shows three links: link 30 (the central horizontal link), link 32 (the left angled link), and link 34 (the right angled link). There are four hinge axes (36) connecting these links. The diagram illustrates the links in a horizontal position and two curved arrows indicating rotational movement around the hinge axes. Labels include 'Hinge Axis', 'Central Axis', and 'Reference Axis'.

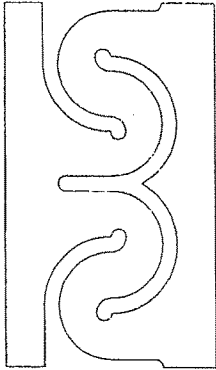
FIG. 2



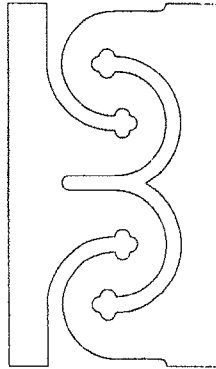
Variant 1



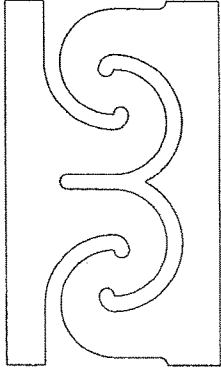
Variant 4



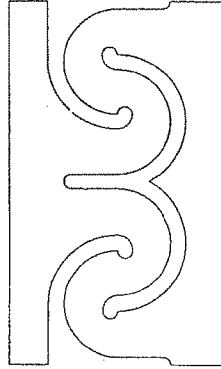
Variant 2



Variant 5



Variant 3



Variant 6

FIG. 3

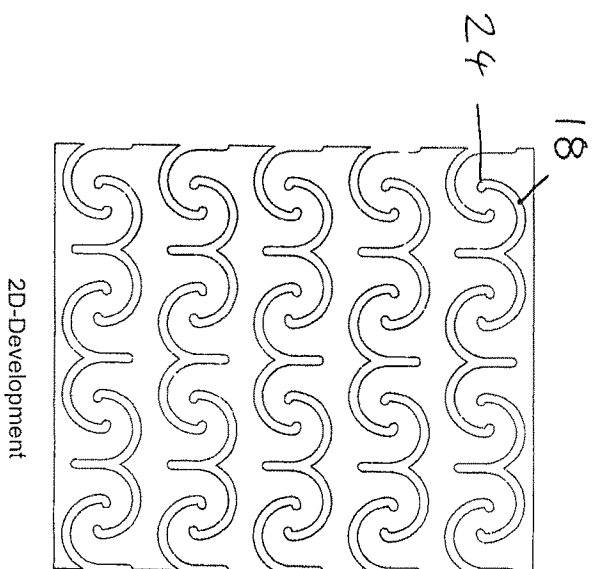


FIG. 4A

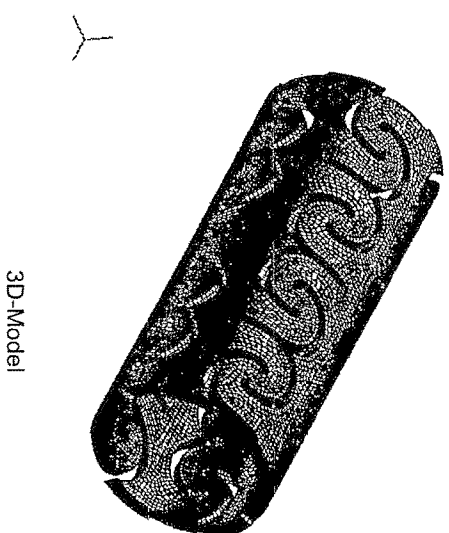


FIG. 4B

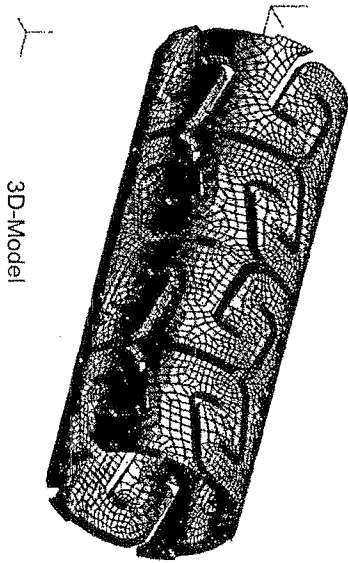
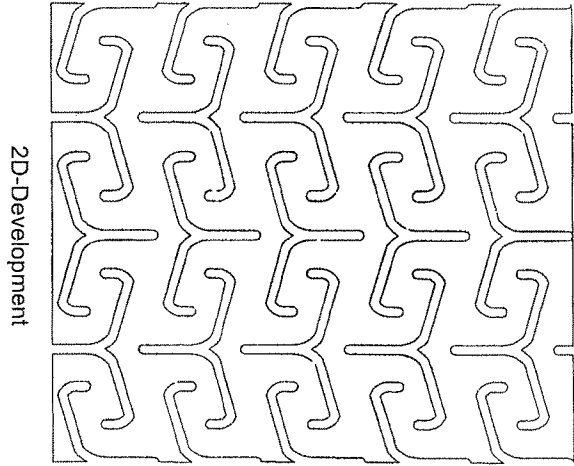


FIG. 5A

FIG. 5B

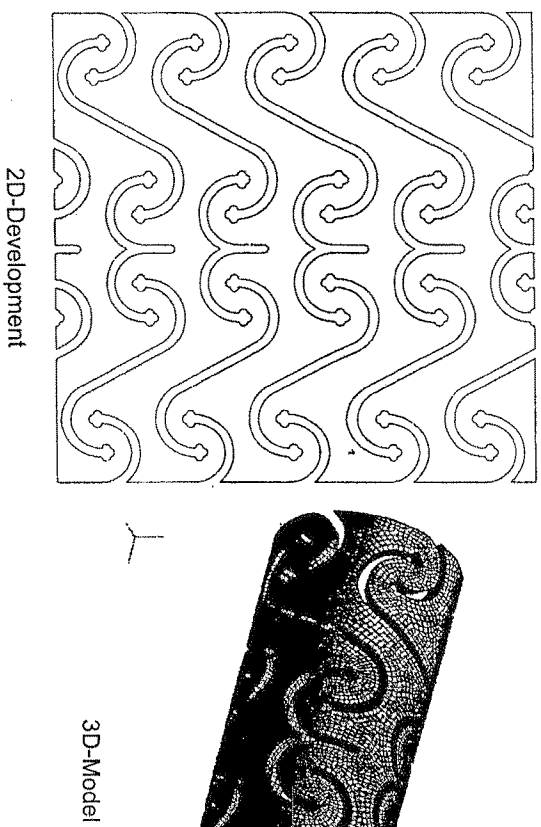
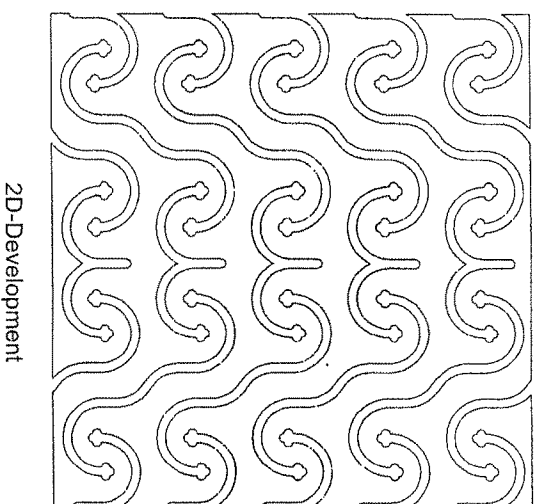


FIG. 6A



FIG. 6B

7/13



2D-Development



3D-Model

FIG. 7A

FIG. 7B

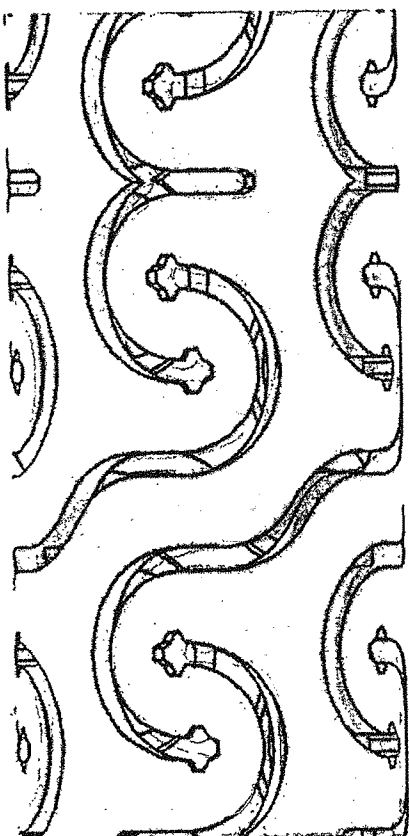


FIG. 8



9/13

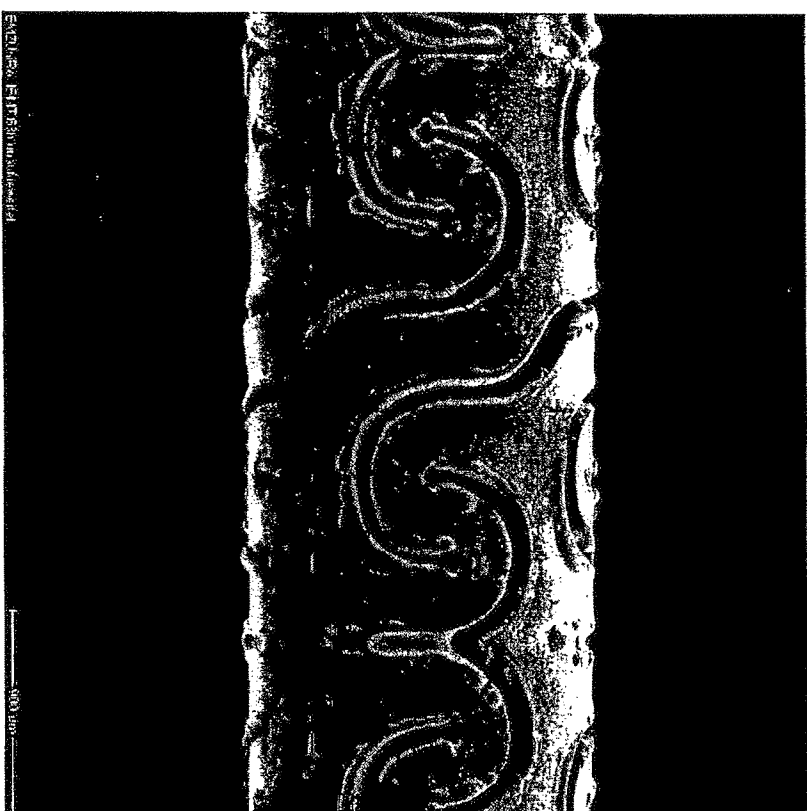


FIG. 9

10/13

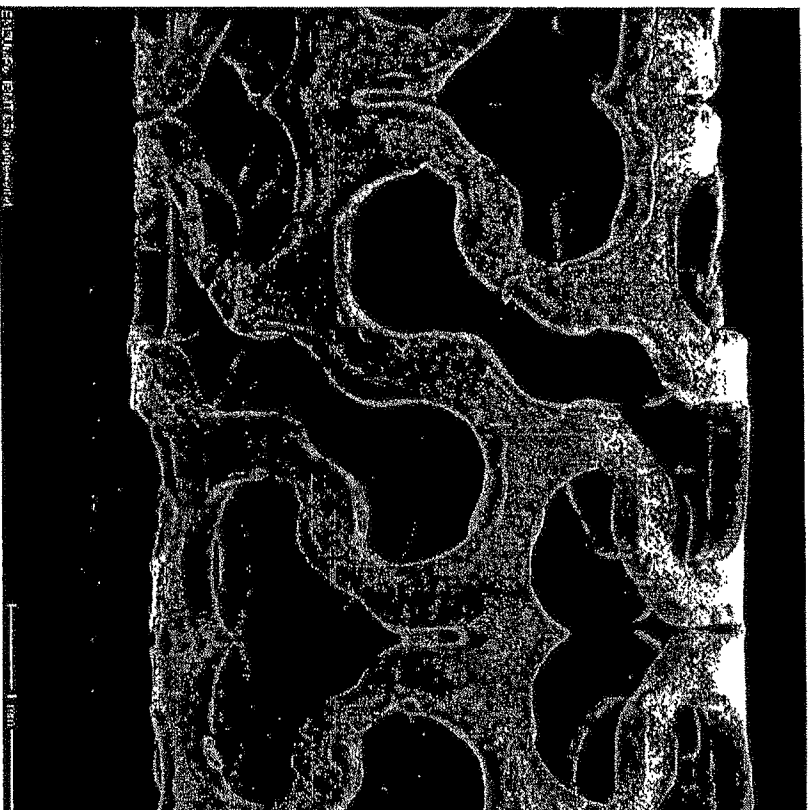


FIG. 10

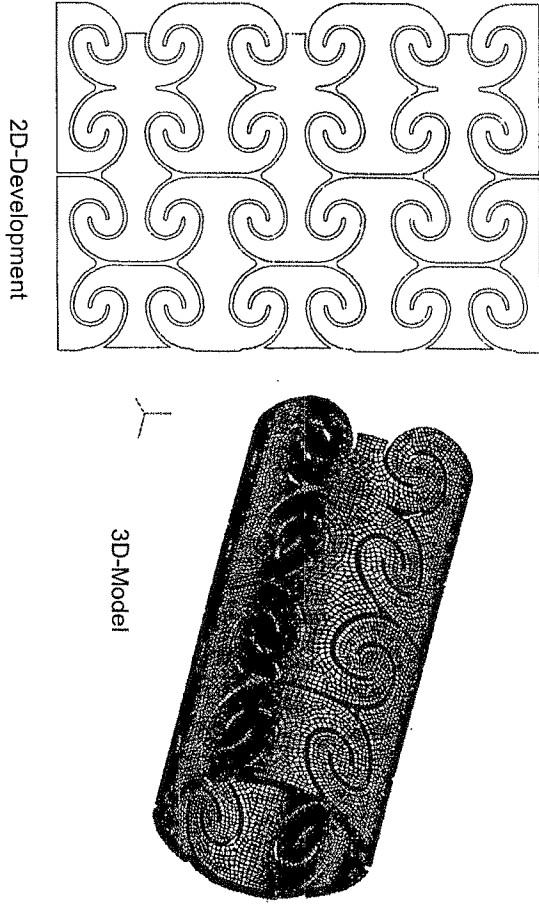


FIG. 11A

FIG. 11B

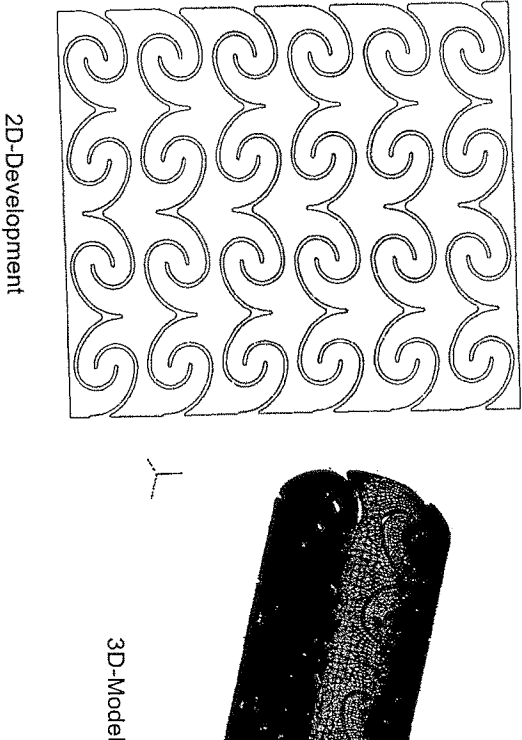


FIG. 12A

FIG. 12B

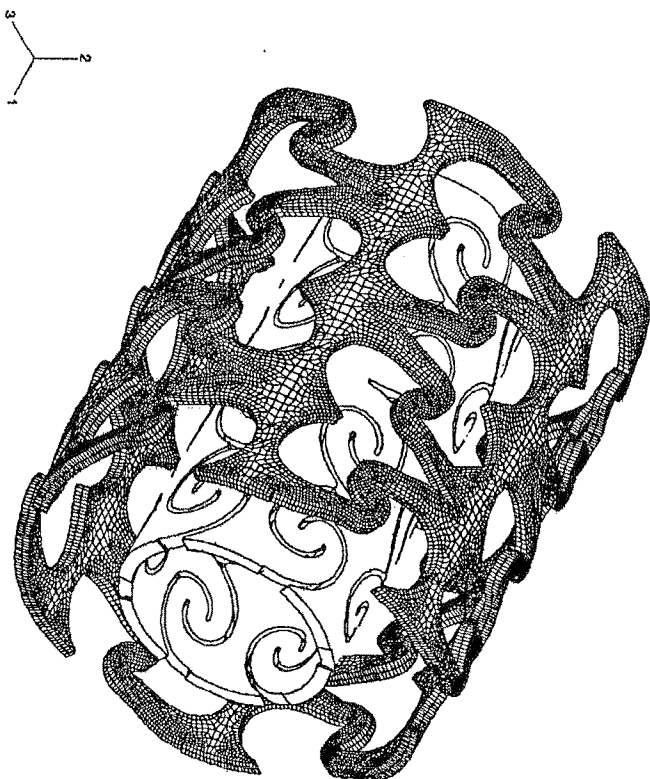


FIG. 13A

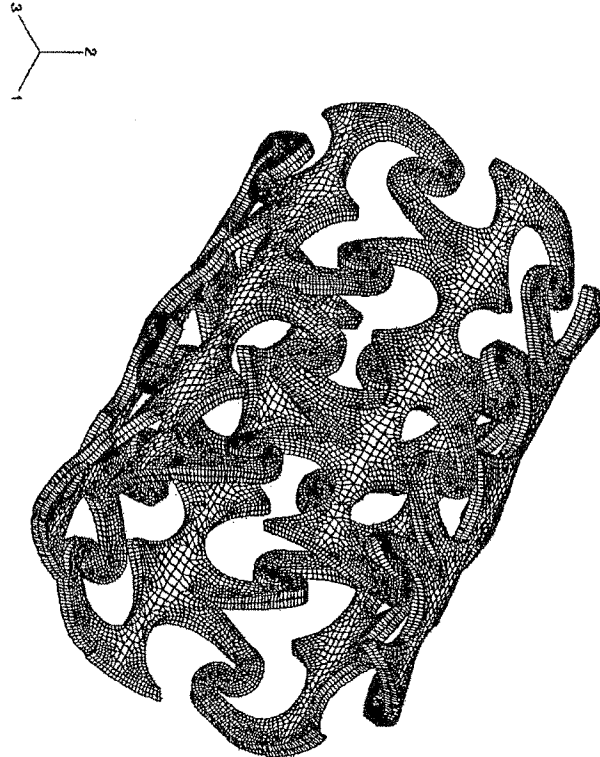


FIG. 13B